

システム設計のための Sパラメタモデリングに関する考察

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September 2020



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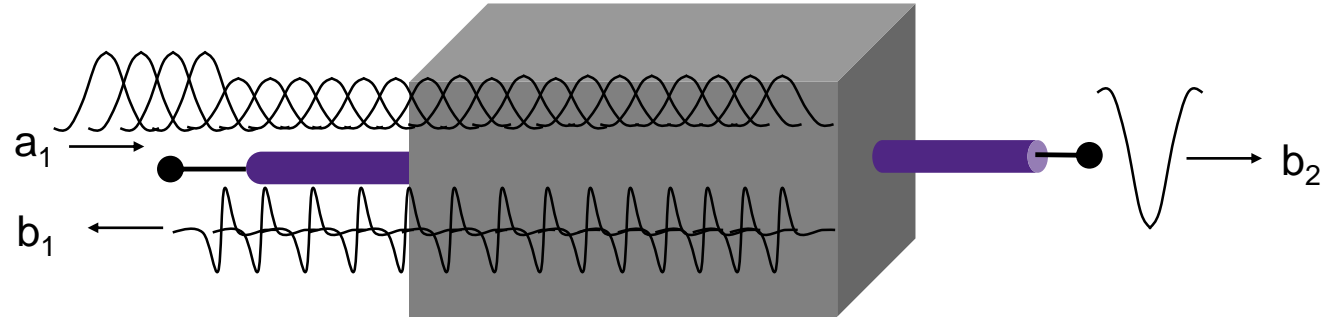
- Introduction
- S-parameter Quality Assessments
 - Checking Causality
- Tips in s-parameter modeling
 - Decoupling Capacitor
 - Multi-segment Transmission Lines
 - Focusing on Partial Network in Large Systems
- Summary

Introductions

S-parameter definitions and insights



Road to the S-parameters

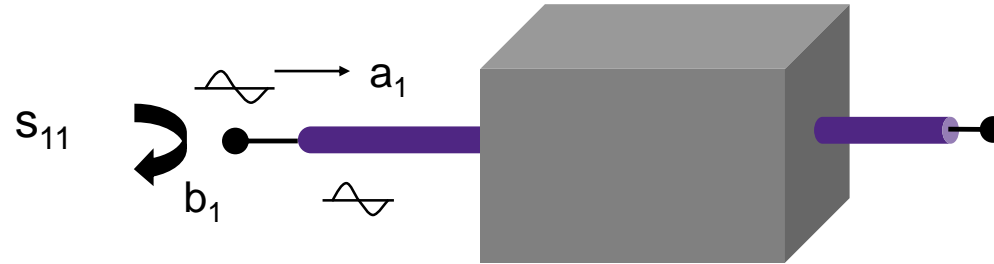


- Simplifying transmission line (EM wave propagation) theory
 - Values for voltage $v(x,t)$ and current $i(x,t)$ along the line can vary dramatically, so they are hard to deal with.
 - A more useful approach is to consider the RF signal as a sum of incident (“ a ”) and reflected (“ b ”) traveling voltage waves.

$$a_1 \sim V_{inc} e^{j(\omega t - \beta x)}$$

$$b_1 \sim V_{ref} e^{j(\omega t + \beta x)}$$

Scattering Parameters



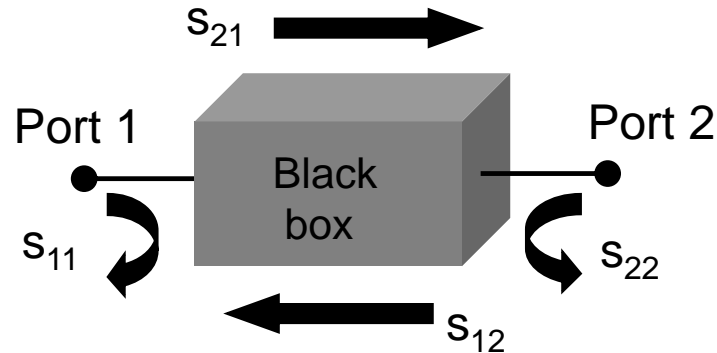
- *S-parameters* represent the complex ratios of these incident and reflected (scattered) voltage waves at a given frequency, e.g.

$$s_{11} = \frac{b_1}{a_1}$$

○○○○ Simpler algebra

- S-parameters are complex numbers: we can make useful calculations using complex arithmetic.
- S-parameters are easily measured by injecting power and measuring reflected & transmitted signals.

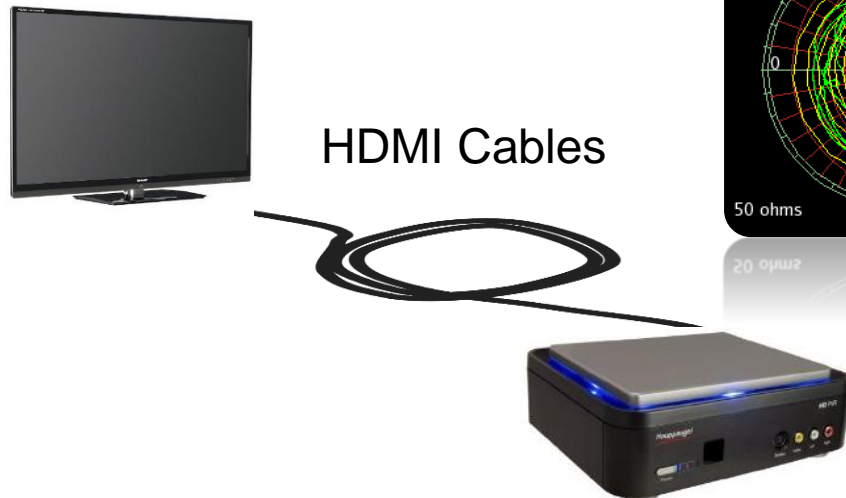
Two-Port Scattering Parameters



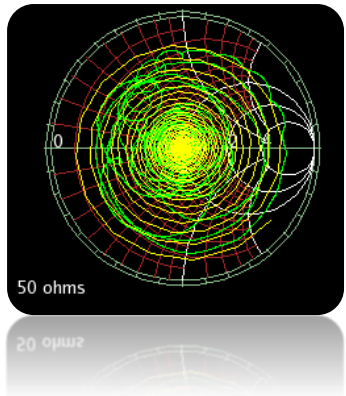
- S_{11} = input reflection coefficient (return loss)
- S_{21} = forward transmission coefficient (gain, Insertion loss)
- S_{12} = reverse transmission coefficient (isolation)
- S_{22} = output reflection coefficient

- S -parameter matrix:
$$\mathbf{S} = \begin{pmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{pmatrix}$$

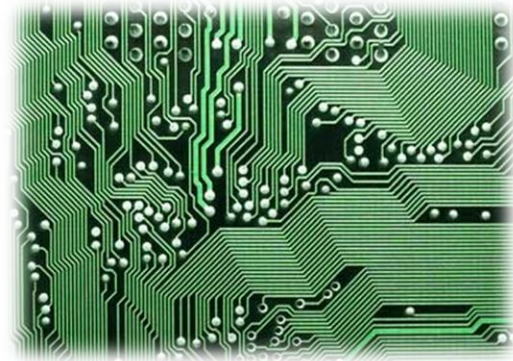
S-Parameter Varieties



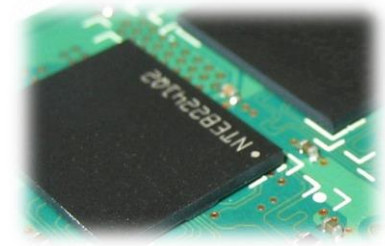
HDMI Cables



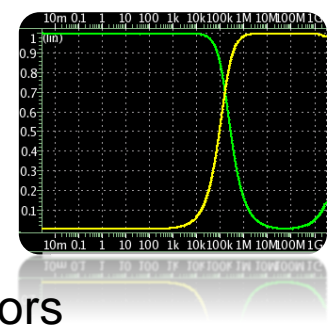
PCB Wires



Ceramic Capacitors



IC Packages



S-parameters Advantages & Challenges

Designers

- Useful in system evaluations

- 😊 Measurable
 - Linear(ized) n-port
 - High frequency coverage
- 😊 Smith Chart Display
 - Passive : $|S_{ij}| \leq 1$
 - Impedance matching

Designers

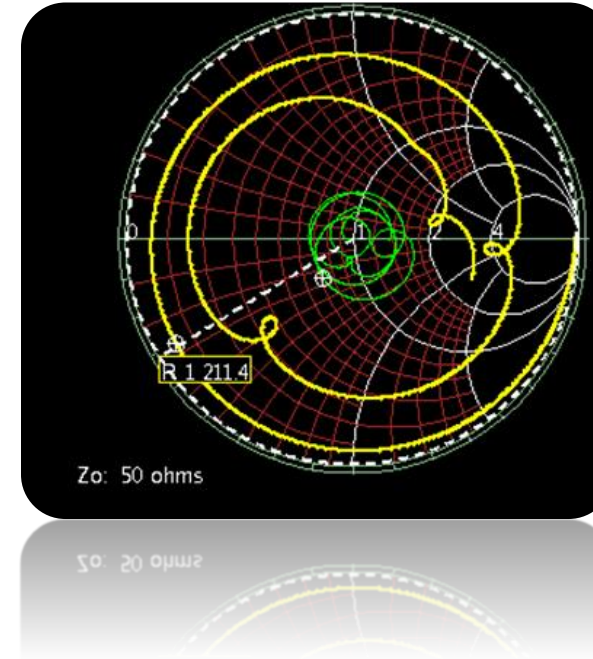
- Useful in IP distribution

- 😊 Black box
- 😊 Distributed network

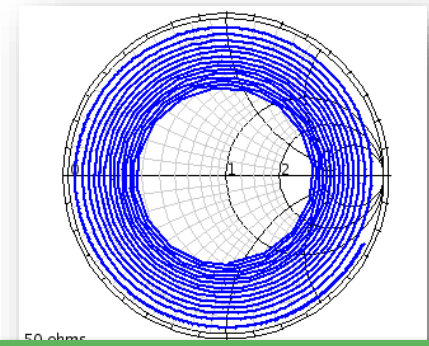
Tools

- Challenges in Simulations

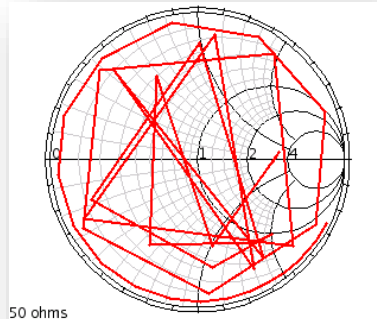
- 😞 Discrete sampling, limited bandwidth
- 😞 Passivity violations, bad terminations
- 😞 $S(f)$ in time domain
- 😞 Black boxed



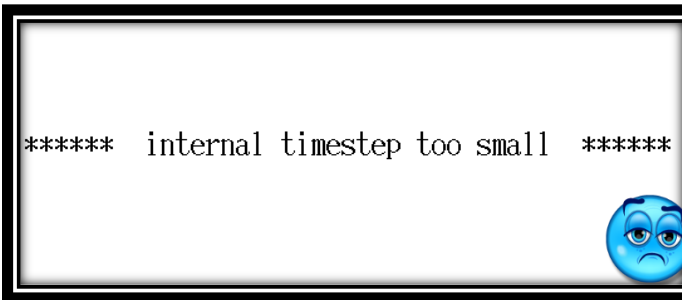
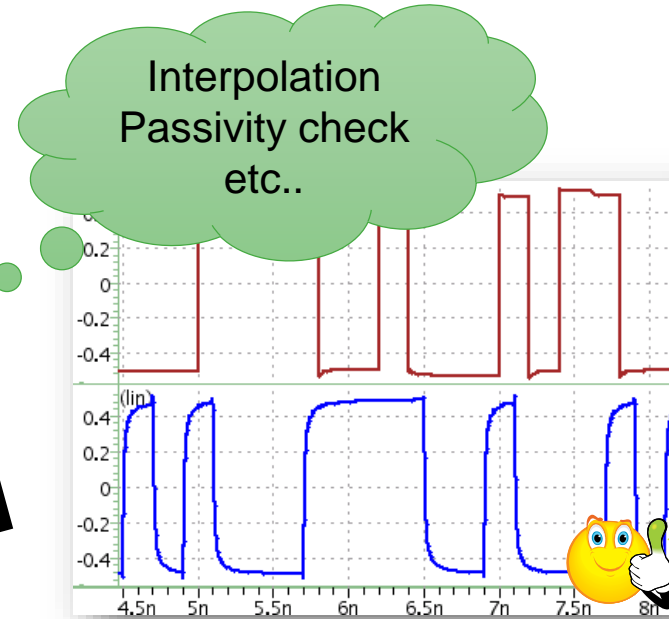
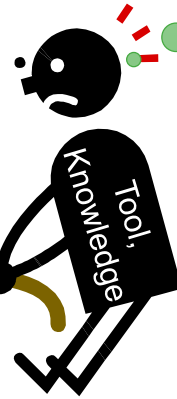
1st Step to Ensure Good Results



good s-parameters

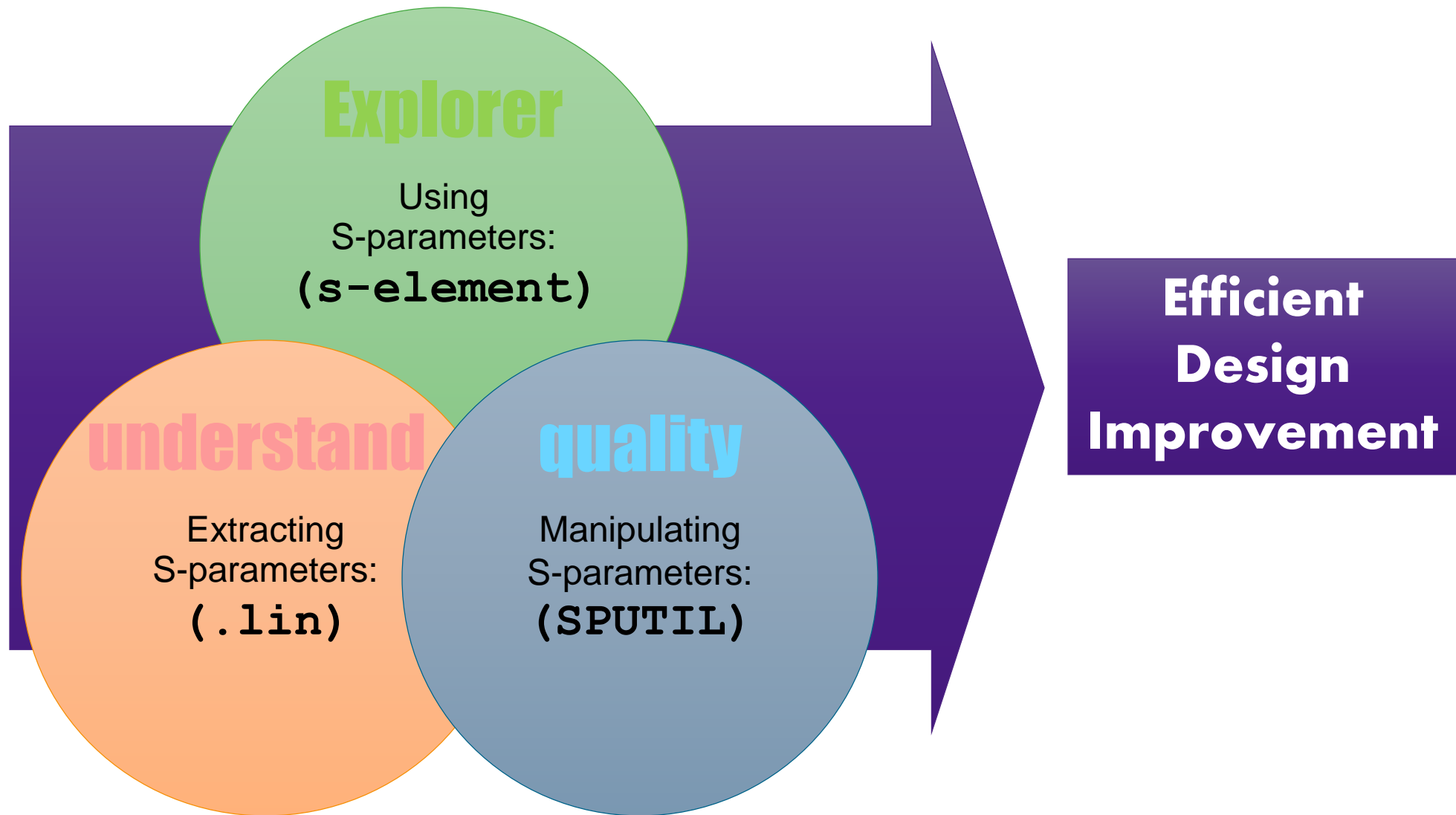


poor s-parameters



Best practice: Please look at your s-parameters before using them

Essentials in Designs with S-parameters



S-parameter Quality Assessments

Passivity, reciprocity, causality and more...



S-parameter Quality Assessment in IEEE P370^[1]

Introduction to the IEEE P370 Standard and its Applications for High Speed Interconnect Characterization

IEEE P370 WorkGroup

DESIGNCON 2020
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WHERE THE CHIP MEETS THE BOARD

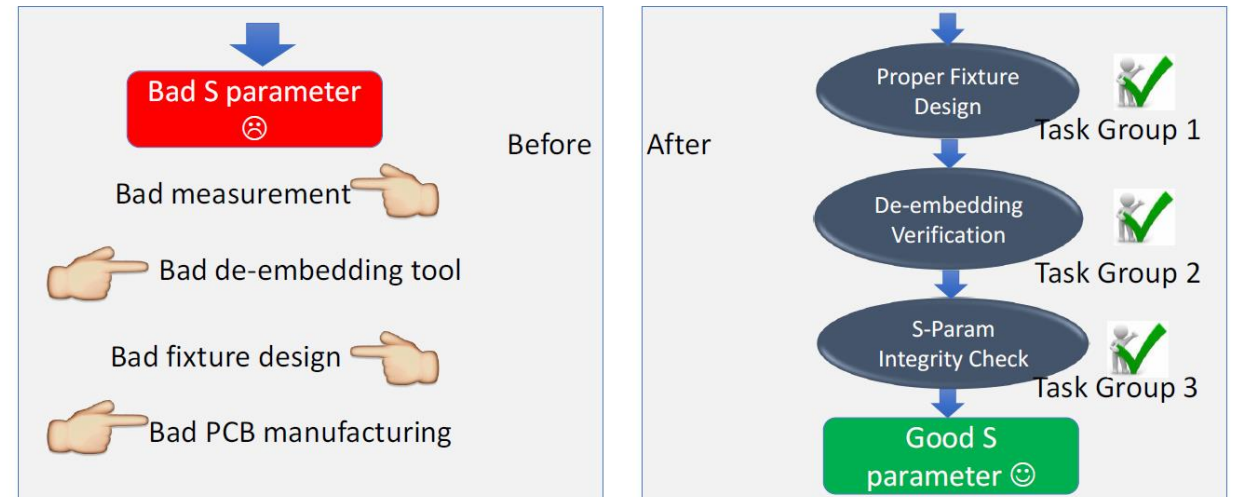


January 28–30, 2020

#DesignCon

informamarkets

P370 Objectives



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January 28–30, 2020

11 informamarkets

[1] IEEE P370 Work Group,
“Introduction to the IEEE P370 Standard and its Applications for High Speed Interconnect Characterization,” DesignCon 2020

S-parameter Quality Assessment in IEEE P370^[1]

TG3: S-parameter Integrity and Validation

Problem statement:

- The quality of measured S-parameters of DUT can vary widely. There is no IEEE standard to check and validate the quality of S-parameters before they are distributed for use.

Key P370 contributions:

- A procedure to evaluate the integrity of S-parameters before distribution
- Quantitative criteria on what is the expected impact of imperfection

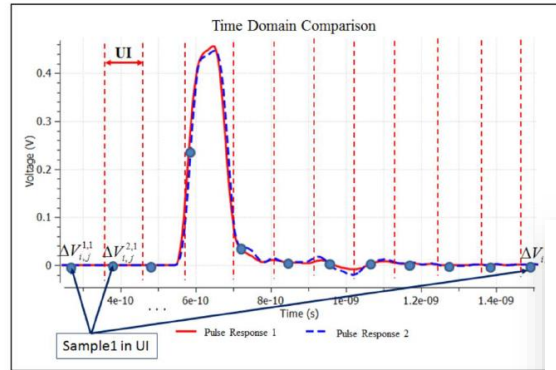
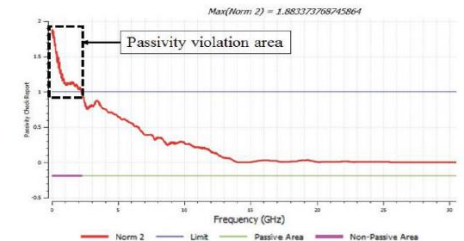
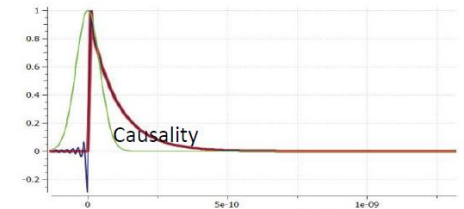


Figure 29 —Time domain estimation in mV unit

S-parameter Quality Estimation

- S-parameters describing a physical system are not perfectly accurate and do not describe it comprehensively;
- It's important to be able to estimate the quality of existing data in order to achieve reliability of the results and conclusions developed based on it
- The goal is to estimate S-parameter quality based on three properties:
 - Passivity
 - Reciprocity
 - Causality



[1] IEEE P370 Work Group,
“Introduction to the IEEE P370 Standard and its Applications for High Speed Interconnect Characterization,” DesignCon 2020



Causality

“consequence should not happen before a cause”



Non-Causality Creates Uncertainty in Transient Sim

- A system is causal if the result (output) comes after the cause (input)
- When system is non-causal, transient (marching in time) analysis cannot identify valid results

$$I_{out}(\omega) = Y(\omega) \cdot V_{in}(\omega)$$

↓

$$out(t) = \int_{-\infty}^{\infty} h(t - \tau) \cdot in(\tau) d\tau$$

Convolution Integral

$out(t)$: output

$in(t)$: input

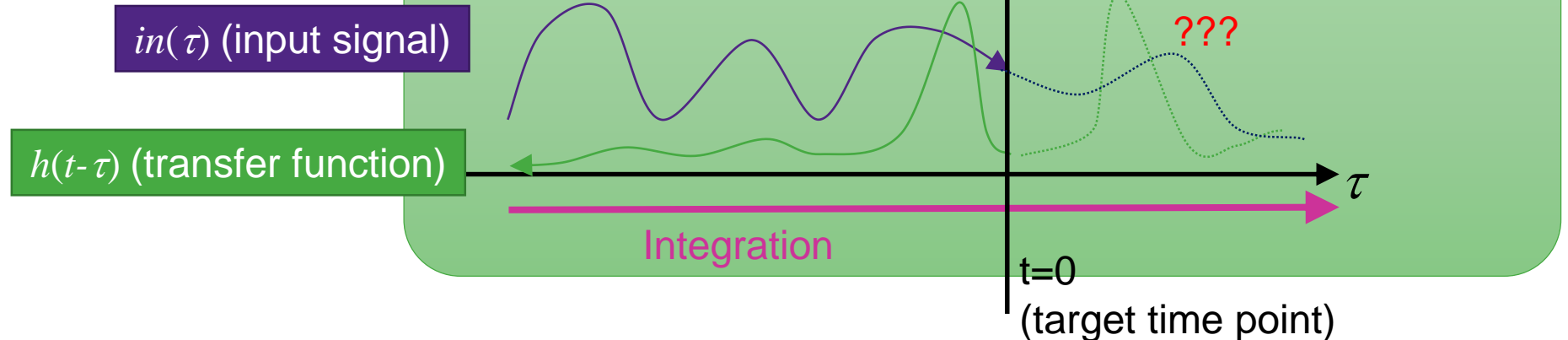
$h(t)$: transfer function

Look at the
output at $t=0$
(for example)

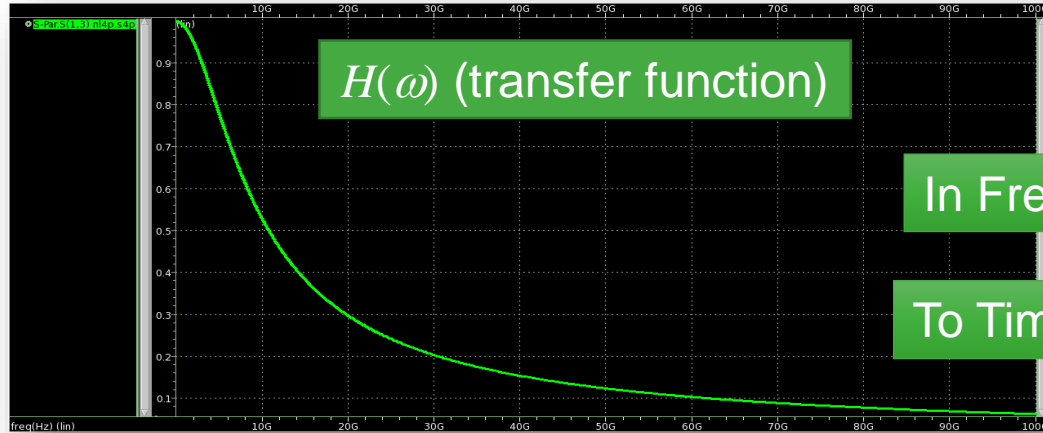
$$out(t=0) = \int_{-\infty}^{\infty} h(-\tau) \cdot in(\tau) d\tau$$
$$= \int_{-\infty}^0 h(-\tau) \cdot in(\tau) d\tau + \int_0^{\infty} h(-\tau) \cdot in(\tau) d\tau$$

Dependency on the past

Dependency on the future!!

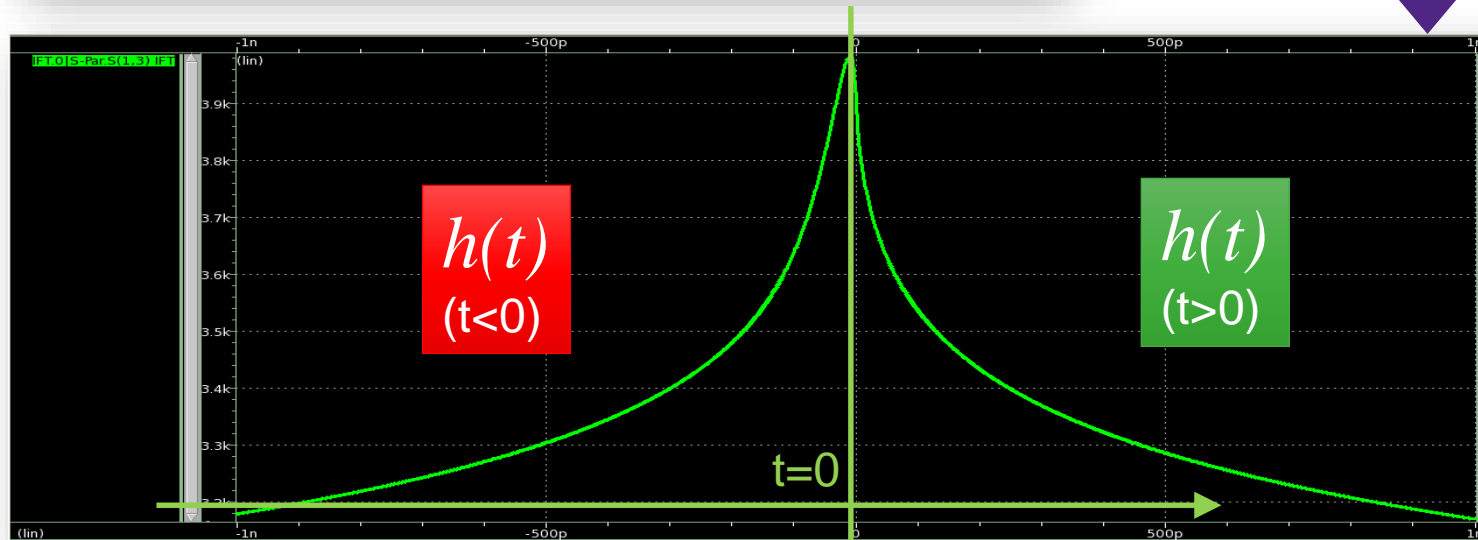


Observing Causality Issue



In Frequency Domain

To Time Domain



Anti-causal part ($h_a(t)$)

Causal part ($h_c(t)$)

Causal function (R_c : real, I_c : imag) satisfies Kramers-Kronig relations (in Frequency domain)

- $R_c(j\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{I_c(j\omega')}{(\omega - \omega')} \cdot d\omega' = H\{I_c(j\omega)\}$
- $I_c(j\omega) = -\frac{1}{\pi} \int_{-\infty}^{\infty} \frac{R_c(j\omega')}{(\omega - \omega')} \cdot d\omega' = -H\{R_c(j\omega)\}$
- Where $H\{\cdot\}$ is the Hilbert Transform.

Typical Causes of non-causal S-Parameters

- Incorrect calibration in measurement
 - E.g. over de-embedding fixture (propagation delay)
- Incorrect physical constant in EM extraction
 - E.g. real-only frequency dependent parameters (skin effect, dielectric loss)
- Insufficient frequency sampling



Tools to Ensure S-parameter Quality (e.g. SPUTIL)

- Format conversion (S/Y/Z Touchstone-v1,v2,CITIfile)
- Merge multiple data files
- Change reference impedance
- Arbitrary re-sampling (w/ inter-/extrapolation, windowing)
- Passivity checker/enforcement
- Causality checker
- Partial view, zero padding (e.g. $S_{dd} \leftrightarrow S_{mixed}$)
- Port swap/reorder/pick
- more...

Causality Checker in SPUTIL

```
TSTONEFILE my_sparam.s2p  
CAUSAL check
```

SPUTIL

- SPUTIL automatically decomposes given system s-parameters into causal and anti-causal part using discrete Hilbert transform in frequency domain
- Feature Selected Validation (FSV) to judge if given data set is causal enough, resulting in the Global Difference Measure (GDM)
- eGDM is a gaussian mapping of average GDM.

eGDM roughly tells :

$0.20 \geq eGDM : \text{poor.}$

$0.65 \geq eGDM > 0.2 : \text{fair.}$

$1.0 \geq eGDM > 0.65 : \text{good.}$

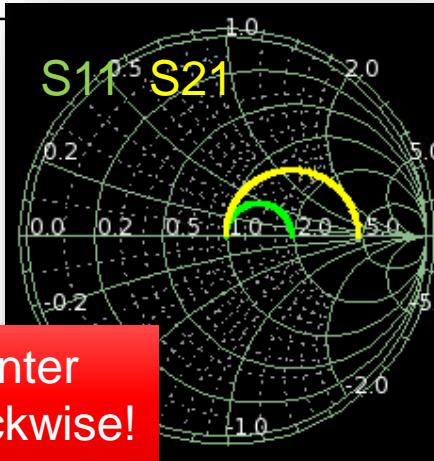
Causality Checker Example

```
P1 1 0 port=1
P2 2 0 port=2
```

```
R1 1 2 50
C1 2 0 -1n
```

DUT

```
.lin format=touchstone
.ac sweepblock=my_swp
.sweepblock my_swp
+ POI 1 0.0
+ DEC 100 1e3 1e9
```



```
S[2,1] avg eGDM is: 1.23e-07
S[1,1] avg eGDM is: 1.23e-07
```

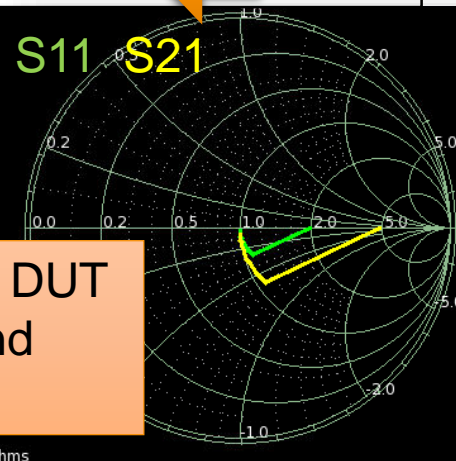
```
P1 1 0 port=1
P2 2 0 port=2
```

```
R1 1 2 50
C1 2 0 1n
```

DUT

corrected

```
.lin format=touchstone
.ac sweepblock=my_swp
.sweepblock my_swp
+ POI 1 0.0
+ DEC 20 1e7 1e8
```



```
S[1,1] avg eGDM is: 0.653
S[2,1] avg eGDM is: 0.653
```

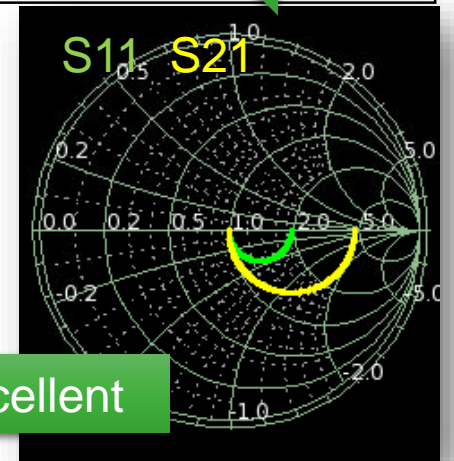
```
P1 1 0 port=1
P2 2 0 port=2
```

```
R1 1 2 50
C1 2 0 1n
```

DUT

widened

```
.lin format=touchstone
.ac sweepblock=my_swp
.sweepblock my_swp
+ POI 1 0.0
+ DEC 200 1e3 20e9
```



```
S[1,1] avg eGDM is: 0.977
S[2,1] avg eGDM is: 0.977
```

Tips in S-parameter Modeling

For High Speed System Designs



[background] Time Domain Analysis with S-parameters



Time-Domain Simulation with Scattering Parameters

$$I_{out}(\omega) = Y(\omega) \cdot V_{in}(\omega) \quad (\text{Eq. 1})$$

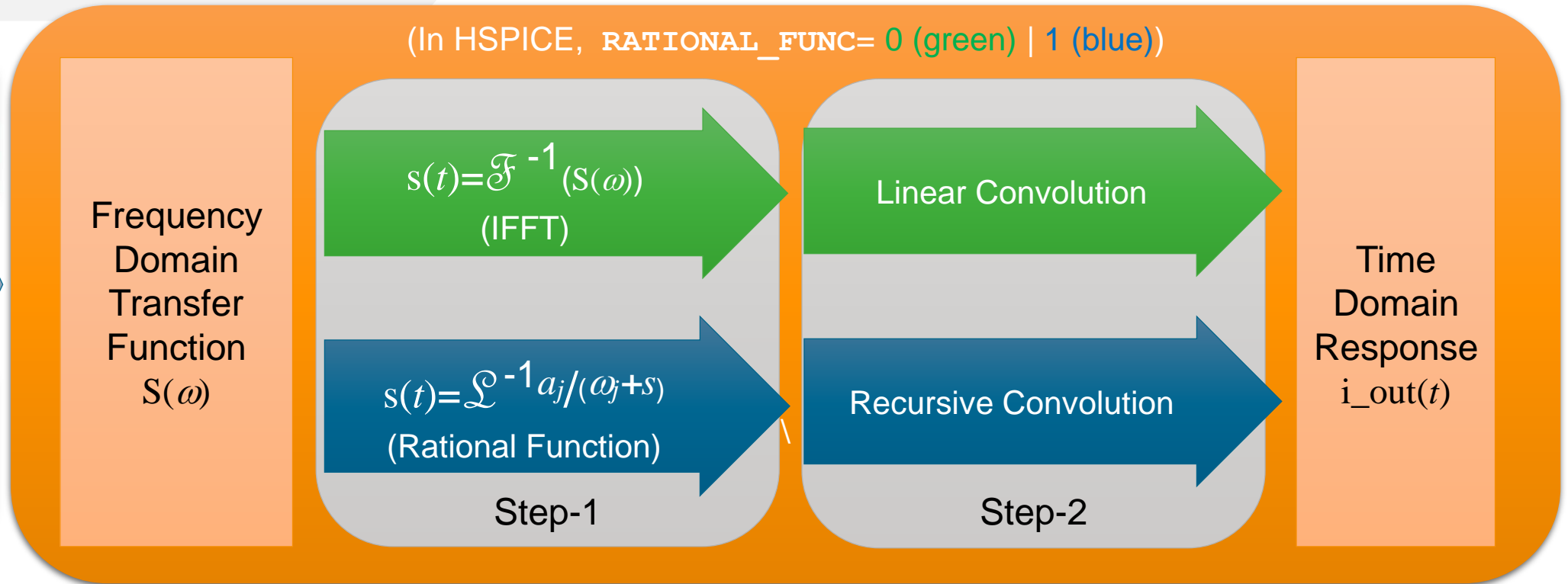
↓ convolution

$$i_{out}(t) = v_{in}(t) * y(t) \\ = \int_{-\infty}^t y(t-\tau) \cdot v_{in}(\tau) d\tau \quad (\text{Eq. 2})$$

- Requires two step analysis
 - Step-1 : prepare transfer function in time domain
 - Step-2 : perform convolution integral to get time domain output



Device Under Test (DUT)



Rational Function Modeling

$$\text{output } y(t_n) = \int_{t_0}^{t_n} h(t_n - \tau) \cdot \text{input } x(\tau) d\tau$$

Linear Convolution (Eq. 2)

$$H(\omega) \cong \frac{1}{\omega_o + s}$$

Rational
Function

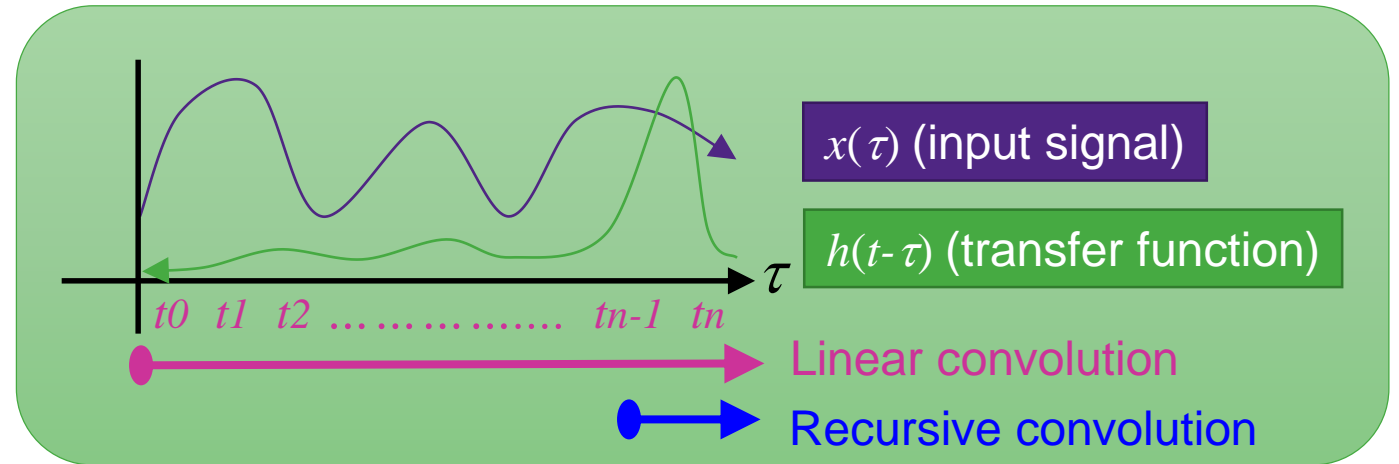
$$h(t) = e^{-\omega_o t}$$

(Eq. 3)

$$y(t_n) = e^{-\omega_o \Delta t} \cdot \text{state variable } y(t_{n-1}) + \int_{t_{n-1}}^{t_n} h(t_n - \tau) \cdot x(\tau) d\tau$$

latest response

Recursive convolution



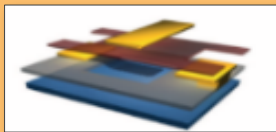
Rational function modeling is ideal for SI/PI simulations

Transient Simulations for SI/PI Analyses

Modeling Challenges

Parasitic Capacitance

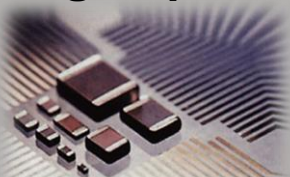
GHz



- Determines [psec] responses

Decoupling Capacitors

kHz

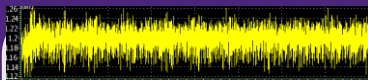


- Determines [msec] stability

High Speed System

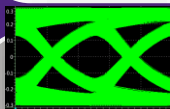


Simulation Challenges



Power Integrity

- SSO analysis to capture both spikes[psec] & drifts[msec] on supply line with deCap



Signal Integrity

- Million bit PRBS analysis to capture extremely low BER

PRBS transient sim runtime

Linear Convolution (*)

Recursive Convolution (*)

500 bits	32 sec	1 sec
5,000 bits	6.4 min	22 sec
50,000 bits	3.5 hr	195 sec

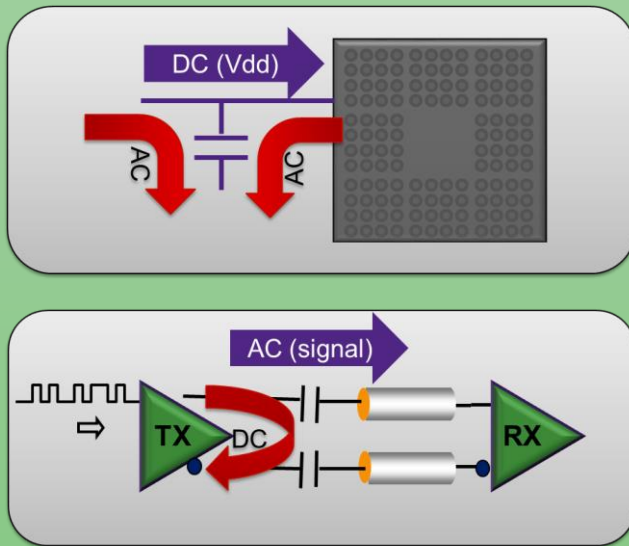
60x

Tip 1 : Decoupling Capacitor

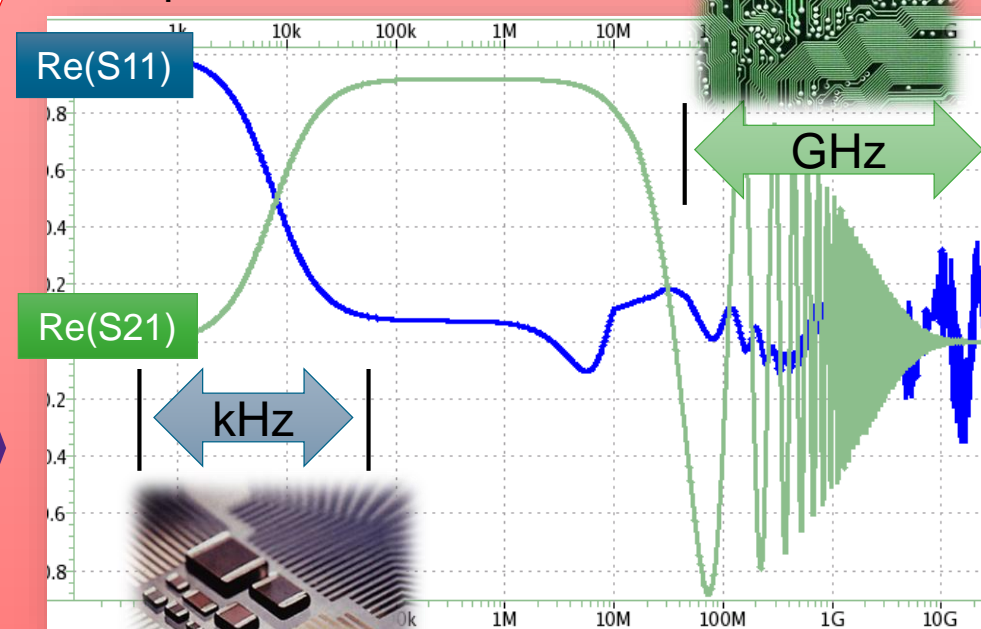


deCap Creates Ultra-Low Frequency Effect

- **Decoupling Capacitor** : a **capacitor** used to **decouple** one part of an electrical network (circuit) from another. (Wikipedia)

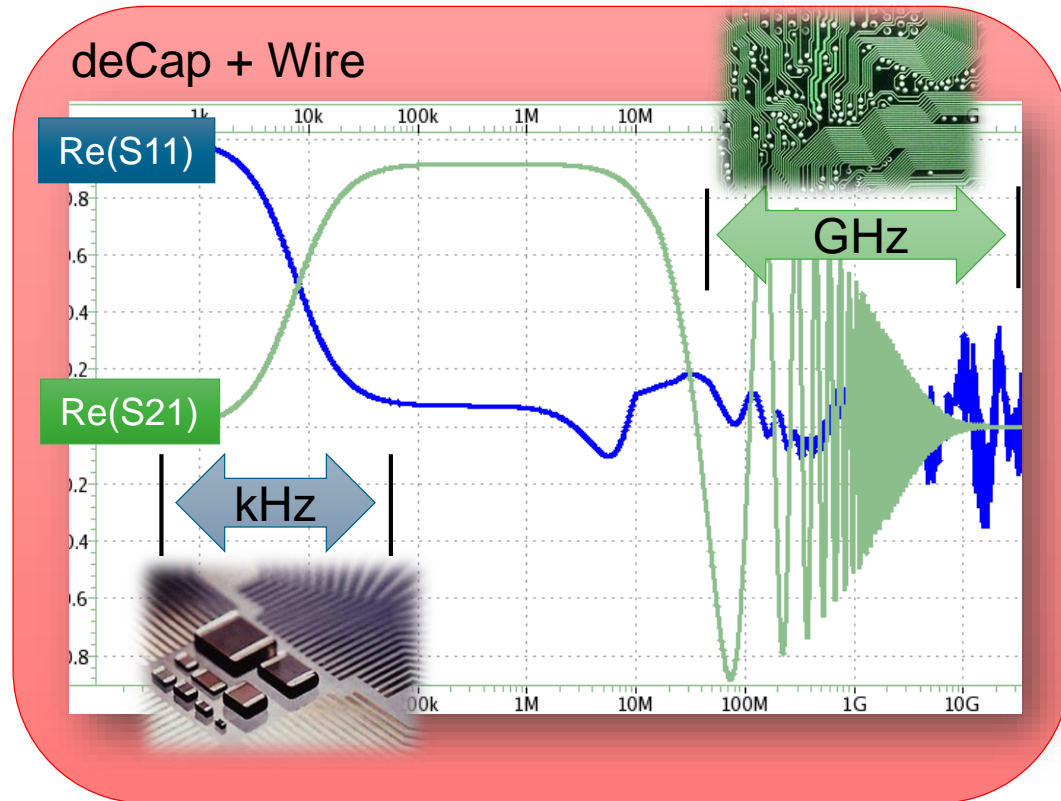


deCap + Wire

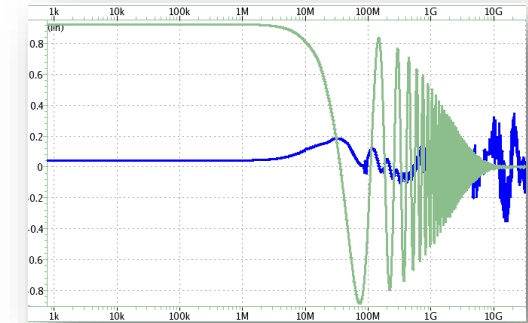


Model separation
→ Accurate sim, convenient for optimization

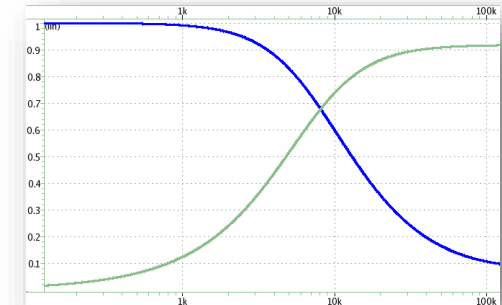
Recommendation: Model Separation



model-1
(wire)



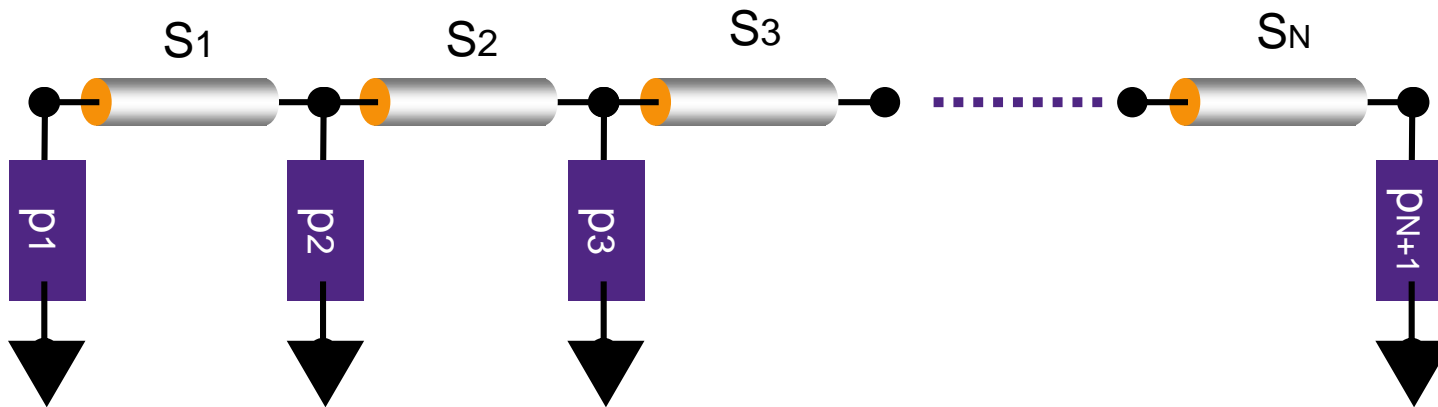
model-2
(deCap)



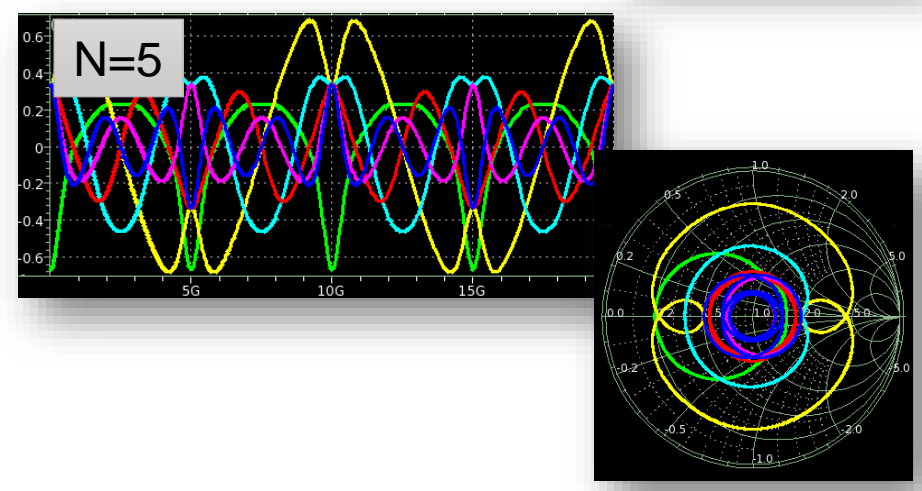
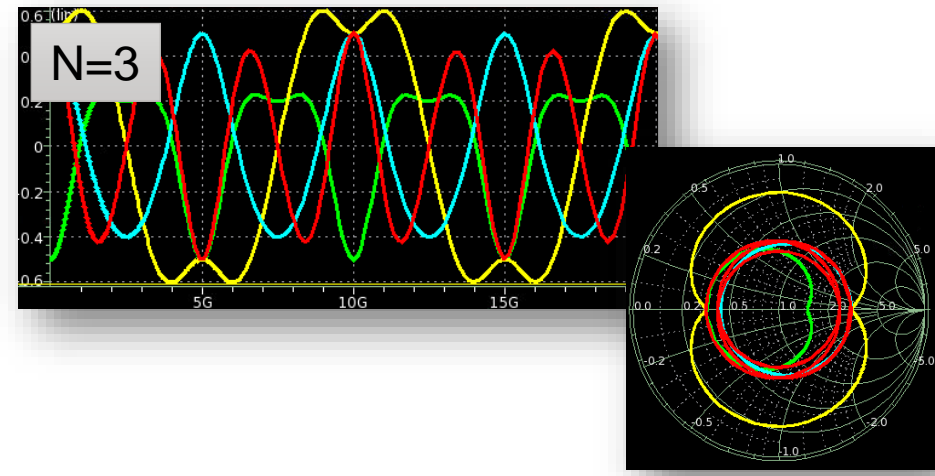
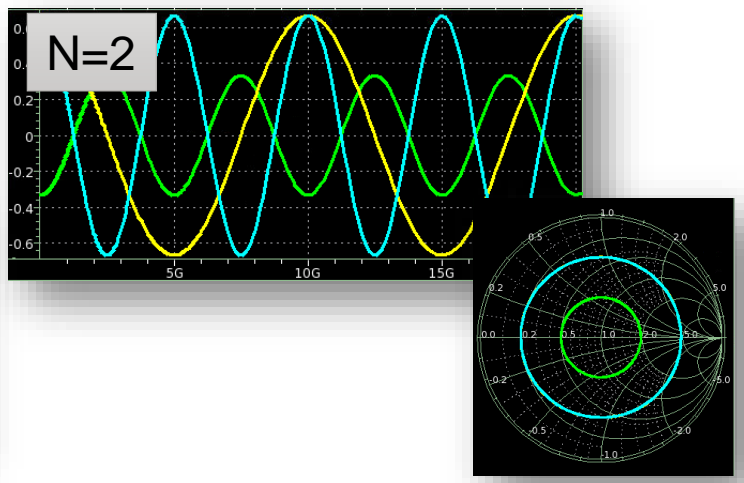
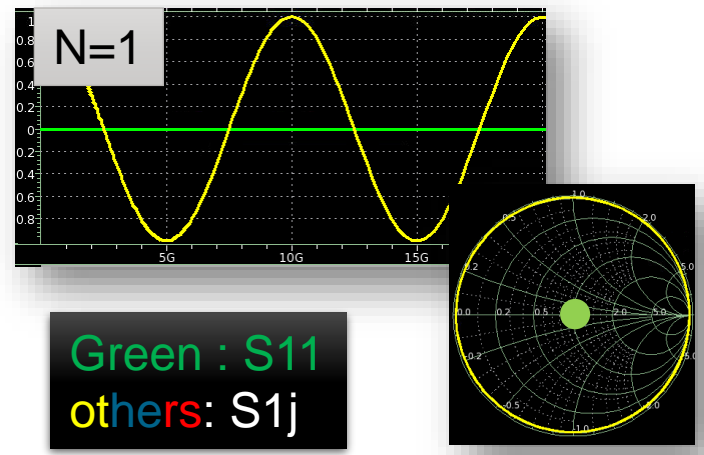
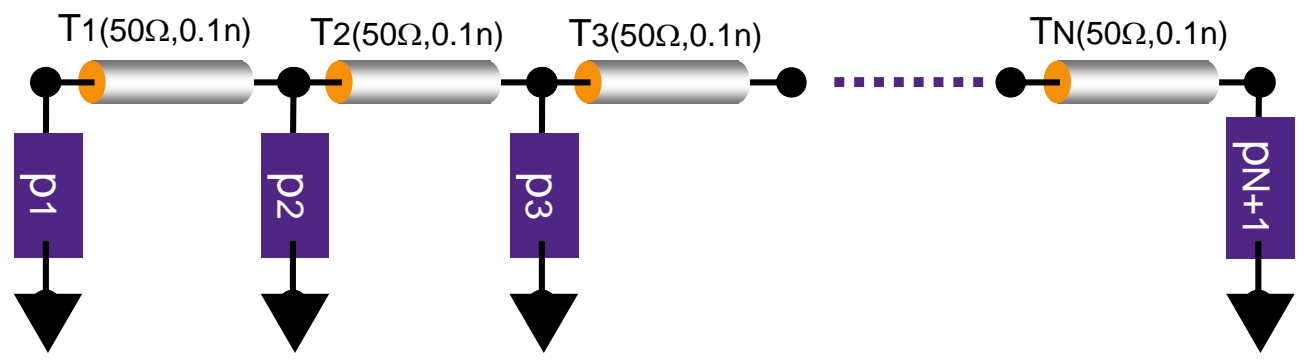
Model separation
→ Fast/Accurate simulation
→ convenient for optimization

Tip 2 : Multi Segment Transmission Lines

Cascading short transmission line segments drastically increase the s-parameter complexity



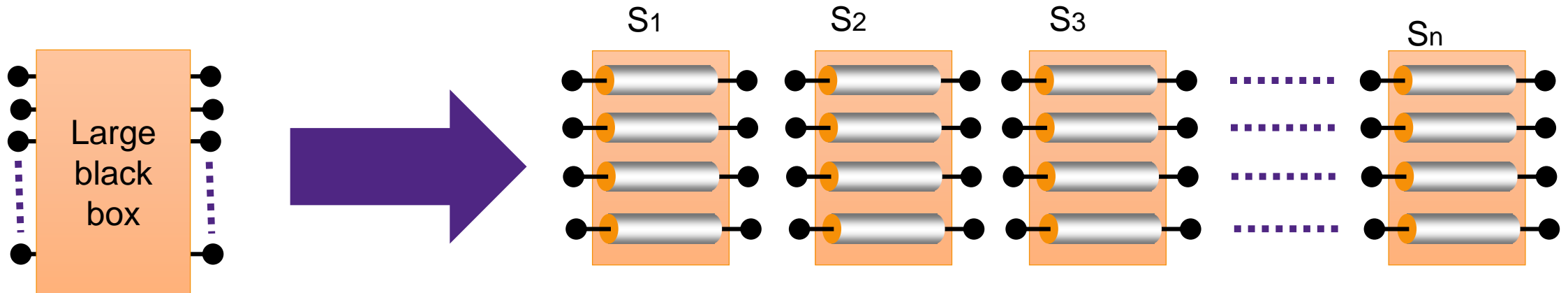
Understanding Multi-Drop S-parameters



# segment	1	2	3	4	20	n
$S(i,i)$	0	-0.33	-0.5	-0.6	-0.91	$-(n-1)/(n+1)$
$S(i,x)$	1	0.66	0.5	0.33	0.095	$2/(n+1)$

Recommendation: Model Separation

When possible, separate s-parameter for each bus segment is recommended

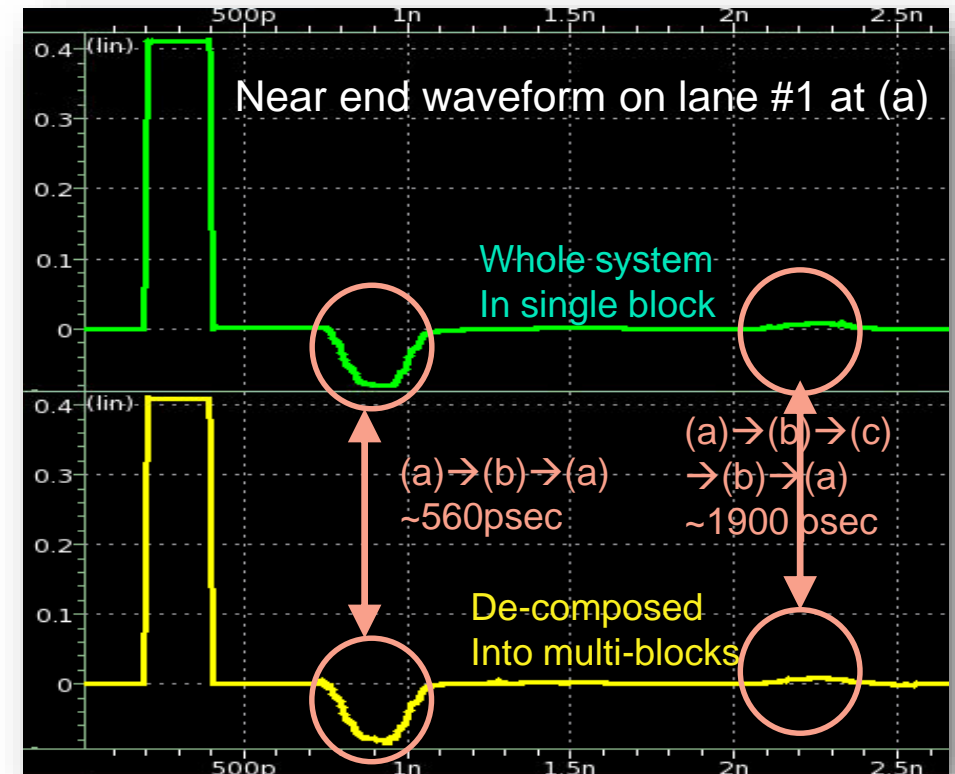
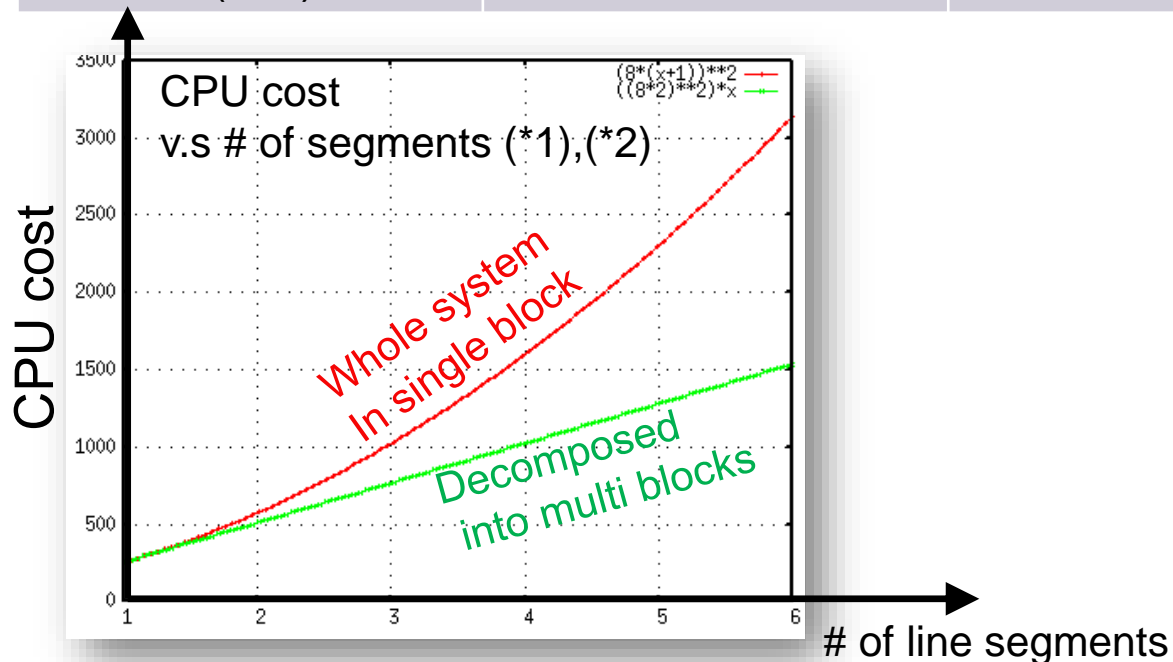


Simulation Performance with Model Separation

Performance and Accuracy

- Performance benefit w/ model separation
- Accuracy preserved

	one 12 port s-parameter block	two 8 port s-parameter blocks
1000 bit transient runtime (sec)	69.1	41.51



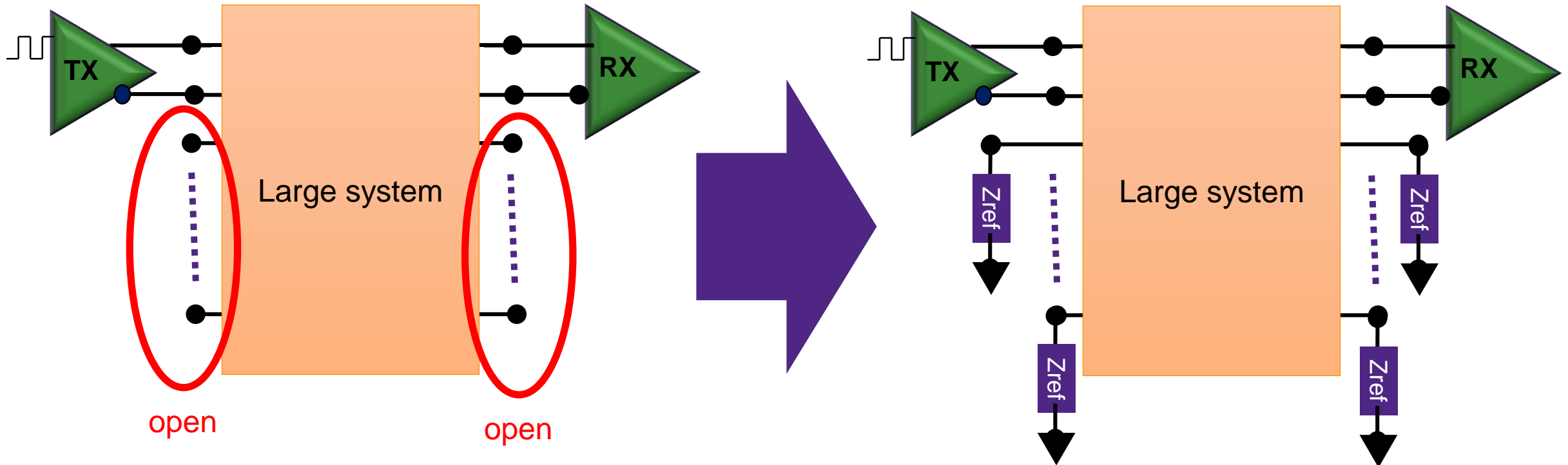
- (*1) These plots assume the same waveform complexity
(*2) Difference may further increase because of high complexity of multi-drop system in single block

Tip 3 : Focusing on Partial Network in Large Systems



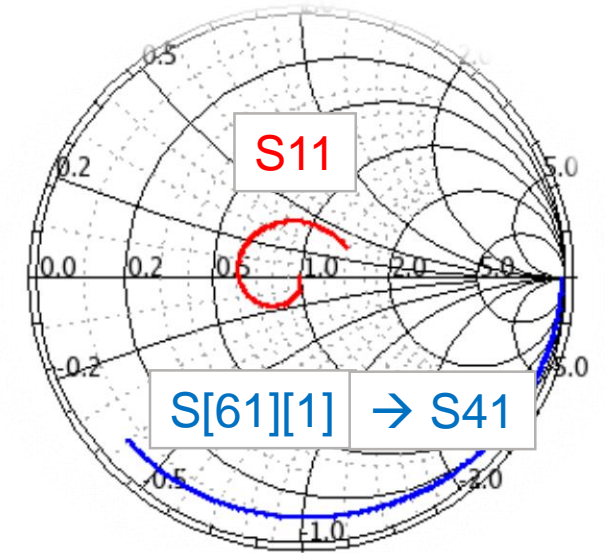
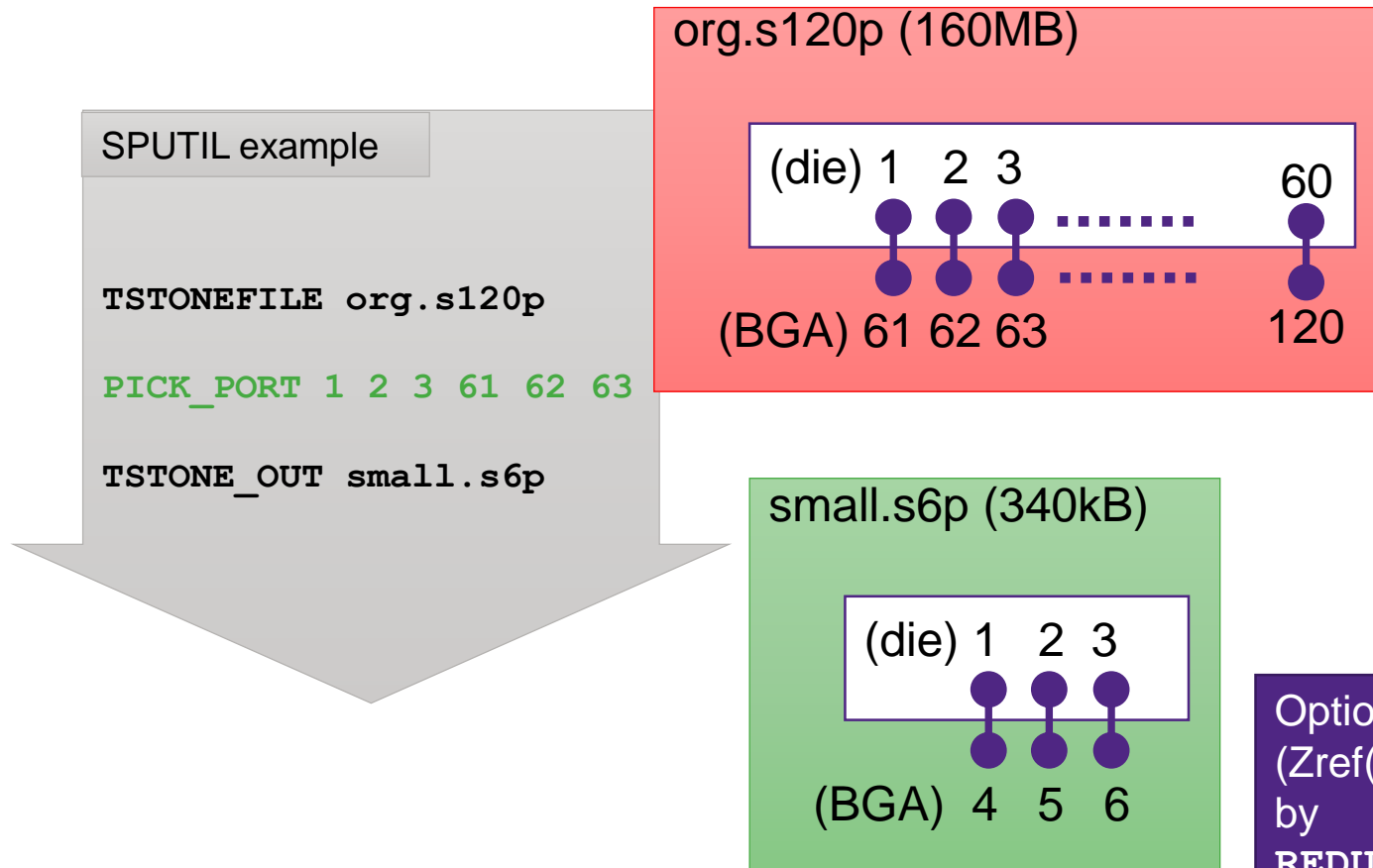
Approach 1: Terminating Unused Ports

- In testing a subset of a big system, many unused s-parameter ports tend to be left open
- Adding proper termination would help simulation stability
 - Add terminations manually
 - Let tools to handle them (*)



Approach 2: Partial Use of Large Systems

- Efficient way for preliminary test
 - Smaller data size, fewer pins → quicker simulation setup & run



Optionally choose termination condition
(Zref(default)/open/short) of port to be removed
by
REDUCE_W_OPEN *indices*
REDUCE_W_SHORT *indices*

Summary

- Introduction
 - Increasing Variation and Complexity in S-parameter modeling
- S-parameter Quality Assessments
 - Passivity, Causality and Reciprocity
- Tips in s-parameter modeling
 - Decoupling Capacitor
 - Multi-segment Transmission Lines
 - Focusing on Partial Network in Large System

Design Success:

- Good Designers
- Good Tools
- Good Understandings

Thank You

